Choreographies		

# Towards Refinable Choreographies

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W3C service choreography:



A major issue with choreographies is lack of modularity

"The basic pattern of my approach will be to compose the program in minute steps, deciding each time as little as possible. As the problem analysis proceeds, so does the further refinement of my program"

E. W. Dijkstra: Notes on Structured Programming

We propose a framework of step-by-step refinement of abstract choreographies into concrete ones

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# Global choreographies

Syntax of global choreographies (g-choreographies for short),  $\mathcal{G}$ :

$$\mathsf{G} ::= \mathbf{0} \mid \mathsf{A} \xrightarrow{\mathsf{m}} \mathsf{B} \mid \mathsf{G}; \mathsf{G}' \mid \mathsf{G} \mid \mathsf{G}' \mid \mathsf{G} + \mathsf{G}'$$

Example:

$$C \xrightarrow{md} S + C \xrightarrow{req} S; S \xrightarrow{done} C$$

Adding refinable (and multiple) interaction:

$$G ::= \cdots \mid A^{\underset{m_1 \dots m_n}{\dots}} B_1 \dots B_n$$

Which are legal refinements of the following?

$$\mathsf{C}^{\mathsf{md}}_{\mathsf{---+}}\mathsf{S} + \mathsf{C}^{\mathsf{req}}_{\mathsf{---+}}\mathsf{S};\mathsf{S}^{\mathsf{done}}_{\mathsf{---++}}\mathsf{C}$$

Sound and wrong refinements:

$$C \xrightarrow{md} S + C \xrightarrow{req} S; (S \xrightarrow{stats} C; S \xrightarrow{done} C) \qquad \checkmark$$

$$(C \xrightarrow{md} B; B \xrightarrow{md} S) + C \xrightarrow{req} S; (S \xrightarrow{stats} C; S \xrightarrow{done} C) \qquad \checkmark$$

$$C \xrightarrow{md} B; B \xrightarrow{md} S) + (C \xrightarrow{start} B; B \xrightarrow{req} S); (S \xrightarrow{stats} C; S \xrightarrow{done} C) \qquad \checkmark$$

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#### Well-formed choreographies

 $\llbracket G \rrbracket = \begin{cases} \mathcal{E} & \text{if certain conditions are satisfied} \\ \bot & \text{otherwise} \end{cases}$ 

where  $\mathcal{E} = (\mathcal{E}, \leq, \#, \lambda)$  is a labelled (prime) event structure, namely  $(\mathcal{E}, \leq)$  is a poset,  $\# \subseteq \mathcal{E}^2$  s.t. for all  $e, e', e'' \in \mathcal{E}$ :

 $\{e' \in E \mid e' \leq e\}$  is finite  $e \# e' \& e' \leq e'' \Longrightarrow e \# e''$ 

 $\lambda: \mathbf{E} 
ightarrow \mathcal{M}$  with

 $\lambda(e) = A B!m$  "A sends m to B" (whose subject is A)  $\lambda(e) = A B?m$  "B receives m from A" (whose subject is B)

We say that G is well-formed if  $\llbracket G \rrbracket \neq \bot$ .

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### Well-branched choice

A branch of  $\mathcal{E} = (E, \leq, \#, \lambda)$  is a maximal subest  $x \subseteq E$  of conflict free events (also called a maximal configuration)

 $[\![\mathsf{G}_1]\!]=\mathcal{E}_1$  and  $[\![\mathsf{G}_2]\!]=\mathcal{E}_2$  are well-branched if

there is a unique  $\ensuremath{\textit{active}}\xspace A$  that locally and unambiguously decides which branch to take in a choice

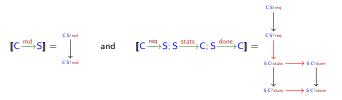
all  $B \neq A$  either behaves the same in all branches, or its behaviour functionally depends on the messages it receives on each branch A opted for: these are **passive** 

where the actives and passives are participants of  $G_1$ ,  $G_2$  (and so subjects of labels of  $\mathcal{E}_1$ ,  $\mathcal{E}_2$ )

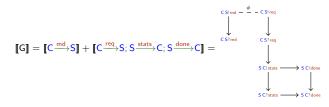
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A well-formed choreography

 $\mathsf{Consider}\;\mathsf{G}=\mathsf{C}\xrightarrow{\mathsf{md}}\mathsf{S}\;\mathsf{+}\;\mathsf{C}\xrightarrow{\mathsf{req}}\mathsf{S};\mathsf{S}\xrightarrow{\mathsf{stats}}\mathsf{C};\mathsf{S}\xrightarrow{\mathsf{done}}\mathsf{C}$ 



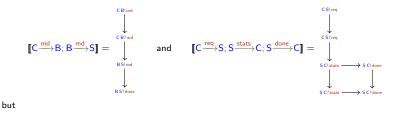
The sum operation on event structures introduces conflicts between the events in  $[C \xrightarrow{md} S]$  and those in  $[C \xrightarrow{req} S; S \xrightarrow{stats} C; S \xrightarrow{done} C]$ , hence:

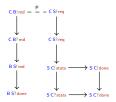


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#### Breaking well-branchedness

 $\text{On the contrary } \mathsf{G}' = \mathsf{C} \xrightarrow{\mathsf{md}} \mathsf{B}; \mathsf{B} \xrightarrow{\mathsf{md}} \mathsf{S} + \mathsf{C} \xrightarrow{\mathsf{req}} \mathsf{S}; \mathsf{S} \xrightarrow{\mathsf{done}} \mathsf{C}$ 





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is not well-branched because of B which is not passive in the right branch

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## Abstracting properties of well-formed choreographies

To determine when  $\llbracket \mathsf{G}_1 \odot \mathsf{G}_2 \rrbracket \neq \bot$  it suffices to know:

the set  $\Pi_i$  of participants of  $\mathsf{G}_i$ 

the set  $\phi_i = \min(\llbracket G_i \rrbracket \upharpoonright A)$  of the (labels of) the minimal events in the projection of  $\llbracket G_i \rrbracket$  to A, for all  $A \in \Pi_i$ 

the set  $\Lambda_i = \mathsf{max}(\llbracket G_i \rrbracket \upharpoonright A)$  of the (labels of) the maximal events in the projection of  $\llbracket G_i \rrbracket$  to A, for all A  $\in \Pi_i$ 

#### Idea

We introduce a typing judgement

$$\Pi \vdash \mathsf{G} : \langle \phi, \Lambda \rangle$$

meaning that  $\Pi = \mathcal{P}(G)$ ,  $\phi$  and  $\Lambda$  are the minimal and maximal actions of all participants in G respectively, and define typing rules that are sound w.r.t. well-formedness

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# Type rules for interaction and sequencing

$$\frac{\phi = \Lambda = \{A B!m, A B?m\}}{\{A, B\} \vdash A \xrightarrow{m} B : \langle \phi, \Lambda \rangle}$$

$$\frac{\Pi_{1} \vdash \mathsf{G}_{1}: \langle \phi_{1}, \Lambda_{1} \rangle \qquad \Pi_{2} \vdash \mathsf{G}_{2}: \langle \phi_{2}, \Lambda_{2} \rangle}{\Pi_{1} \cup \Pi_{2} \vdash \mathsf{G}_{1}; \mathsf{G}_{2}: \langle \phi_{1} \cup (\phi_{2} - \Pi_{1}), \Lambda_{2} \cup (\Lambda_{1} - \Pi_{2}) \rangle}^{\text{T-SEQ}}$$

where for  $L \subseteq \mathcal{L}$  and  $\Pi \subseteq \mathcal{P}$  we set  $L - \Pi = \{ l \in L \mid sbj \ l \not\in \Pi \}$ 

Example:

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Type rule for	choice		

Let  $\widehat{L}(A) = \{ I \in L \mid sbj \mid I = A \}$  for  $L \subseteq \mathcal{L}$ 

 $\frac{\Pi \vdash \mathsf{G}_1 : \langle \phi_1, \Lambda_1 \rangle \qquad \Pi \vdash \mathsf{G}_2 : \langle \phi_2, \Lambda_2 \rangle \qquad \phi_1 \bowtie_{\Pi} \phi_2}{\Pi \vdash \mathsf{G}_1 + \mathsf{G}_2 : \langle \phi_1 \cup \phi_2, \Lambda_1 \cup \Lambda_2 \rangle} \ {}_{^{\mathrm{T-CH}}}$ 

where the condition  $\phi_1 \bowtie_{\Pi} \phi_2$  is defined by the clauses:

there is a unique  $A \in \Pi$  such that  $\widehat{\phi}_1(A)$  and  $\widehat{\phi}_2(A)$  are disjoint sets of output actions and both non-empty;

for all  $B \neq A \in \Pi$ ,  $\widehat{\phi_1}(B)$  and  $\widehat{\phi_2}(B)$  are disjoint sets of input actions and  $\widehat{\phi_1}(B) = \emptyset$  if and only if  $\widehat{\phi_2}(B) = \emptyset$ 

Example:

where  $\phi_2 = \Lambda_2 = \{CS!req, CS?req\}$  and  $\phi_3 = \Lambda_3 = \{CB!md, CB?md\}$ 

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# The type system

$$\frac{\phi = \Lambda = \{A \mid \mathbf{B} \mid \mathbf{m}, A \mid B^{*}\}_{T-INT}}{\{A, B\} \vdash A \xrightarrow{\mathbf{m}} B : \langle \phi, \Lambda \rangle}$$

$$\frac{\Pi_{1} \vdash \mathsf{G}_{1}: \langle \phi_{1}, \Lambda_{1} \rangle \qquad \Pi_{2} \vdash \mathsf{G}_{2}: \langle \phi_{2}, \Lambda_{2} \rangle}{\Pi_{1} \cup \Pi_{2} \vdash \mathsf{G}_{1}; \mathsf{G}_{2}: \langle \phi_{1} \cup (\phi_{2} - \Pi_{1}), \Lambda_{2} \cup (\Lambda_{1} - \Pi_{2}) \rangle} \xrightarrow{_{\mathrm{T-SEQ}}}$$

$$\frac{\Pi_{1} \vdash \mathsf{G}_{1} : \langle \phi_{1}, \Lambda_{1} \rangle \qquad \Pi_{2} \vdash \mathsf{G}_{2} : \langle \phi_{2}, \Lambda_{2} \rangle \qquad \Pi_{1} \cap \Pi_{2} = \emptyset}{\Pi_{1} \cup \Pi_{2} \vdash \mathsf{G}_{1} \mid \mathsf{G}_{2} : \langle \phi_{1} \cup \phi_{2}, \Lambda_{1} \cup \Lambda_{2} \rangle} \xrightarrow{}_{\text{T-PAR}}$$

$$\frac{\Pi \vdash \mathsf{G}_1 : \langle \phi_1, \Lambda_1 \rangle \qquad \Pi \vdash \mathsf{G}_2 : \langle \phi_2, \Lambda_2 \rangle \qquad \phi_1 \bowtie_{\Pi} \phi_2}{\Pi \vdash \mathsf{G}_1 + \mathsf{G}_2 : \langle \phi_1 \cup \phi_2, \Lambda_1 \cup \Lambda_2 \rangle} \xrightarrow{}_{^{\mathrm{T-CH}}}$$

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em (Soundness) G : $\langle \phi, \Lambda  angle$ is derivable then [G]	$ eq \perp$ , $\Pi = \mathcal{P}(G)$ , and	nd	
$\widehat{\phi}(A) = min(\llbracket G \rrbracket \restriction$	A) and $\widehat{\Lambda}(A)$	$max(\llbracket G  rbracket \land A)$	

holds for all  $A \in \Pi$ .

Remark: a choreography G has at most one typing  $\Pi \vdash G : \langle \phi, \Lambda \rangle$  and it is computable

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#### The refinement relation

Let  $A_{--}^{\overline{m}} \to \overline{B} \equiv A_{----}^{m} B_1 \dots B_n$ , then a ground g-choreography G refines  $A_{--}^{\overline{m}} \to \overline{B}$ , written G ref  $A_{--}^{\overline{m}} \to \overline{B}$ , if [G] =  $\mathcal{E} \neq \bot$ ;

sbj min( $\mathcal{E}$ ) = {A}, by which we say that A is the (unique) initiator of G;

for all branch x of  $\mathcal{E}$  and  $1 \leq h \leq n$  there exists  $C \in \mathcal{P}(G)$  such that  $C B_h?m_h \in max(x \upharpoonright B_h)$ 

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## Axioms for refinable interactions

Axiom schema for refinable interactions:

$$\frac{\text{sbj } \phi = \text{sbj } \Lambda = \Pi \quad \text{sbj } (\phi \cap \mathcal{L}^!) = \{A\} \quad \forall h \exists C \in \Pi. \ \widehat{\Lambda}(B_h) = \{C B_h; m_h\} \\ \Pi \vdash A^{-----}_{----} B_1 \dots B_n : \langle \phi, \Lambda \rangle$$

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Let $\Pi$	$I = \{C, S\}:$						
			$\phi_2 = \Lambda_2$	$= \{ CS! req, CS? req \}$	$\phi_3$	$= \Lambda_3 = \{ {{S}  {C} !  {done}, }$	S C?done}
$\phi_1 =$	$\Lambda_1 = \{ {\color{black}{C}}  {\color{black}{S}} !  {\color{black}{m}}$	ld, <mark>C S</mark> ?md}	$\Pi \vdash 0$	$C^{\operatorname{req}} S : \langle \phi_2, \Lambda_2 \rangle$		$\Pi \vdash S^{done}_{} C : \langle \phi \rangle$	$_{3},\Lambda_{3} angle$
$\Pi \vdash C_{}^{req} S : \langle \phi_1, \Lambda_1 \rangle \qquad \qquad \Pi \vdash C_{}^{req} S : S_{}^{done} C : \langle \phi_2, \Lambda_3 \rangle$							
$\Pi \vdash C^{md}_{} S + C^{req}_{} S; S^{done}_{} C : \langle \phi_1 \cup \phi_2, \Lambda_1 \cup \Lambda_3 \rangle \xrightarrow{T-CH} T-CH$							

 $\begin{array}{l} \mbox{Consider } \mathsf{G}_1 \equiv \mathsf{C} \xrightarrow{\mbox{md}} \mathsf{B}; \mathsf{B} \xrightarrow{\mbox{md}} \mathsf{S} \mbox{ s.t. } \mathsf{G}_1 \mbox{ ref } \mathsf{C} \xrightarrow{\mbox{md}} \mathsf{S}, \mbox{ then compute} \\ \\ \Pi \cup \{\mathsf{B}\} \vdash \mathsf{C} \xrightarrow{\mbox{md}} \mathsf{B}; \mathsf{B} \xrightarrow{\mbox{md}} \mathsf{S} : \langle \phi_1 \cup \{\mathsf{C} \mbox{ B} ? \mathsf{md}\}, \Lambda_1 \cup \{ \mathsf{B} \mbox{ S} ! \mathsf{md}\} \rangle \end{array}$ 

Let  $\Pi' = \Pi \cup \{B\}$ ,  $\phi'_1 = \phi_1 \cup \{CB?md\}$ ,  $\Lambda'_1 = \Lambda_1 \cup \{BS!md\}$ ; then

 $\frac{}{\Pi' \vdash \mathsf{C}^{\mathsf{md}}_{- \to} \mathsf{S} : \langle \phi'_1, \Lambda'_1 \rangle}^{\text{T-REF}}$ 

but now rule  $\ensuremath{\mbox{T-CH}}$  doesn't apply since  $\Pi' \neq \Pi$ 

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L	et $\Pi = \{C, S\}$ :				
			$\phi_2 = \Lambda_2 = \{CS!req,CS?req\}$	$\phi_3 = \Lambda_3 = \{ S$	C!done, S C?done}
$\phi_1 = \Lambda_1 = \{CS!md,CS?md\}$		md, C S?md}	$\Pi \vdash C^{req}_{} S : \langle \phi_2, \Lambda_2 \rangle$	$\Pi \vdash S^{done}$	$\rightarrow C: \langle \phi_3, \Lambda_3 \rangle$
$\Pi \vdash C^{req}_{} S : \langle \phi_1, \Lambda_1 \rangle \qquad \qquad \Pi \vdash C^{req}_{} S ; S^{done}_{} C : \langle \phi_2, \Lambda_3 \rangle$					- /
	Г	$I \vdash C \xrightarrow{md} S + C$	$\xrightarrow{req} S; S \xrightarrow{done} C : \langle \phi_1 \cup \phi_2, \Lambda_1 \cup \phi_2 \rangle$	$ \Lambda_3\rangle$	— T-CH

 $\begin{array}{l} \mbox{Consider } \mathsf{G}_1 \equiv \mathsf{C} \xrightarrow{\mbox{md}} \mathsf{B}; \mathsf{B} \xrightarrow{\mbox{md}} \mathsf{S} \mbox{ which is s.t. } \mathsf{G}_1 \mbox{ ref } \mathsf{C} \xrightarrow{\mbox{md}} \mathsf{S}, \mbox{ then compute} \\ \\ \Pi \cup \{\mathsf{B}\} \vdash \mathsf{C} \xrightarrow{\mbox{md}} \mathsf{B}; \mathsf{B} \xrightarrow{\mbox{md}} \mathsf{S} : \langle \phi_1 \cup \{\mathsf{C} \mbox{ B} ? \mbox{md}\}, \Lambda_1 \cup \{ \mathsf{B} \mbox{ S} ! \mbox{md}\} \rangle \end{array}$ 

 $\begin{array}{l} \mbox{Consider } \mathsf{G}_2 \equiv \mathsf{C} \xrightarrow{\times} \mathsf{B}; \mathsf{B} \xrightarrow{\mathsf{req}} \mathsf{S} \mbox{ which is s.t. } \mathsf{G}_2 \mbox{ ref } \mathsf{C} \xrightarrow{\mathsf{req}} \mathsf{S}, \mbox{ and compute} \\ & \Pi' \vdash \mathsf{C} \xrightarrow{\times} \mathsf{B}; \mathsf{B} \xrightarrow{\mathsf{req}} \mathsf{S} : \langle \phi_2', \Lambda_2' \rangle \\ & \mbox{where } \Pi' = \Pi \cup \{\mathsf{B}\}, \ \phi_2' = \{\mathsf{C}\mathsf{B}!\mathsf{x}, \mathsf{C}\mathsf{B}?\mathsf{x}, \mathsf{B}\:\mathsf{S}!\mathsf{rep}\} \mbox{ and } \Lambda_2' = \{\mathsf{C}\mathsf{B}?\mathsf{x}, \mathsf{B}\:\mathsf{S}!\mathsf{rep}, \mathsf{B}\:\mathsf{S}?\mathsf{rep}\}, \mbox{ and } \end{array}$ 

take  $G_3 \equiv S \xrightarrow{\text{done}} C \operatorname{ref} S \xrightarrow{\text{const}} C \operatorname{s.t.}$ 

$$\Pi \vdash \mathsf{S} \xrightarrow{\mathsf{done}} \mathsf{C} \langle \phi_3, \Lambda_3 \rangle$$

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We end up with:

$$\frac{\overline{\Pi' \vdash \mathsf{G}_1: \langle \phi_1', \Lambda_1' \rangle}}{\Pi' \vdash \mathsf{G}_1 + \mathsf{G}_2: \mathsf{G}_3: \langle \phi_2', \Lambda_2' \rangle} \frac{\overline{\Pi \vdash \mathsf{G}_3: \langle \phi_3, \Lambda_3 \rangle}}{\Pi' \vdash \mathsf{G}_2; \mathsf{G}_3: \langle \phi_2', \Lambda_3' \rangle}_{\mathsf{T-CH}}$$

where

$$\mathsf{G}_1 \equiv \mathsf{C} \xrightarrow{\mathsf{md}} \mathsf{B}; \mathsf{B} \xrightarrow{\mathsf{md}} \mathsf{S} \qquad \mathsf{G}_2 \equiv \mathsf{C} \xrightarrow{\times} \mathsf{B}; \mathsf{B} \xrightarrow{\mathsf{req}} \mathsf{S} \qquad \mathsf{G}_3 \equiv \mathsf{S} \xrightarrow{\mathsf{done}} \mathsf{C}$$

and

$$\Pi = \{C, S\} \qquad \Pi' = \Pi \cup \{B\}$$

$$\phi'_1 = \{CS!md, CS?md, CB?md\} \qquad \Lambda'_1 = \{CS!md, CS?md, BS!md\}$$

$$\phi'_2 = \{CB!x, CB?x, BS!rep\} \qquad \Lambda'_2 = \{CB?x, BS!rep, BS?rep\}$$

$$\phi_3 = \Lambda_3 = \{SC!done, SC?done\} \qquad \Lambda'_3 = \Lambda_3 \cup \{BS!rep\}$$

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# Achievements and future work

the type system provides a means to establish which concrete choreographies refine which abstract ones

the mechanism for choosing how to type refinable interactions needs more investigation

we will addres the study of properties of abstract protocols that curry over to concrete ones

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# Thank You

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